



```

$MOD51                ; model seri mikrokontrol 51
    ORG      0000H      ; alamat mulai program
    AJMP    START      ; lompat absolut ke START

    ORG 0023H          ; alamat Interupsi Serial Terima/Kirim RI/TI
    AJMP    Serial_on  ; lompat absolut ke Serial_on

    ORG 0100H          ; lompat absolut ke 100h
START:  MOV SP, #30H    ; isi Stack Pointer dengan nilai 30h
        MOV R4, #30H    ; isi Stack Pointer dengan nilai 30h
        ACALL INITSER   ; lompat absolut ke initserial

;

Serial_on:  PUSH PSW
           PUSH ACC
           JNB RI,$      ; menunggu data serial masuk
           MOV A,SBUF
           CLR RI        ; clear bit Receiver Interupt
           CLR EA        ; clear bit Enable Interupt
           CJNE A,#'w',KR45 ;
           ACALL MAJU20
           ACALL X_Serial
           RETI          ; kembali ke interpsi

KR45:  CJNE A,#'m',KR90 ; bandingkan dengan 'm', tidak sama lompat kr
KR90   ACALL KIRI45     ; jika sama laksanakan lakukan KIRI45
       ACALL X_Serial   ; Kirim Informasi ke PC

KR90:  CJNE A,#'l',KN45
       ACALL KIRI90
       ACALL X_Serial

KN45:  CJNE A,#'t',KN90
       ACALL KANAN45
       ACALL X_Serial

KN90:  CJNE A,#'r',MD
       ACALL KANAN90
       ACALL X_Serial

MD:    CJNE A,#'f',STOP
       ACALL MUNDUR20
       ACALL X_Serial

STOP:  CJNE A,#'s',EXIT
       ACALL BREAK
       ACALL BREAK
       ACALL X_Serial

EXIT:  MOV SBUF,A
       POP ACC

```

KR90

```
POP      PSW
RETI

MAJU20: SETB    P0.1
        SETB    P0.6
        CLR     P0.0
        CLR     P0.7
        MOV     P2, #11000011B
        ACALL  DELAY
        ACALL  DELAY
        ACALL  BREAK

KIRI45: MOV     P2, #11001111B
        SETB    P0.1
        CLR     P0.6
        CLR     P0.0
        CLR     P0.7
        ACALL  DELAY
        ACALL  BREAK

KANAN45: MOV    P2, #11110011B
        CLR     P0.1
        SETB    P0.6
        CLR     P0.0
        CLR     P0.7
        ACALL  DELAY
        ACALL  BREAK

KIRI90: MOV    P2, #00001111B
        SETB    P0.1
        CLR     P0.6
        CLR     P0.0
        SETB    P0.7
        ACALL  DELAY
        ACALL  BREAK

KANAN90: MOV   P2, #11110000B
        CLR     P0.1
        SETB    P0.6
        SETB    P0.0
        CLR     P0.7
        ACALL  DELAY
        ACALL  BREAK

MUNDUR20: MOV  P2, #00111100B
        CLR     P0.1
        CLR     P0.6
        SETB    P0.0
        SETB    P0.7
        ACALL  DELAY
        ACALL  DELAY
```



```
ACALL BREAK
```

```
BREAK: CLR P0.1
        CLR P0.0
        CLR P0.6
        CLR P0.7
        MOV P2, #11111111B
        ACALL DELAY
```

```

; routine tunda waktu
DELAY: MOV R5, #04H ; Isi nilai Register ke-5 dengan 04h
DEL1:  MOV R6, #0FFH ; Isi nilai Register ke-6 dengan 0ffh atau 254
DEL2:  MOV R7, #0FFH ; Isi nilai Register ke-7 dengan 0ffh atau 254
        DJNZ R7, $ ; kurangi 1 register ke-7
        DJNZ R6, DEL2 ; kurangi 1 register ke-6, bila hasil belum sama
dengan 0 maka lompat ke DEL2
        DJNZ R5, DEL1 ; kurangi 1 register ke-5, bila hasil belum sama
dengan 0 maka lompat ke DEL1
        RET ; kembali ke alamat setelah ACALL DELAY
```

```

INITSER: ; routine Inisialisasi Serial
        MOV SCON, #50H ; serial port mode bit 1 & Receiver Enable
        MOV TMOD, #20H ; Timer 1 mode 2; 8-bit auto-reload
        MOV TL1, #0FDH ; Timer Low, nilai akan berhitung sampai #0FFH
        MOV TH1, #0FDH ; Timer High Reset, Nilai = #0FDH
        SETB TR1 ; Timer 1 RUN
        MOV PCON, #00H ; hidupkan power control
        MOV IE, #90H ; Enable Serial Port Interrupt
        SETB ES
        RET ; kembali ke alamat setelah ACALL INITSER
```

```

X_Serial: MOV SBUF, A ; pindahkan isi accumulator k buffer port serial
          JNB TI, $ ; jeda hingga bit RI diatur
          CLR TI ; clear Transmit Interupsi
          SETB EA ; Set bit Enable Interupt
          RETI ; kembali ke interpsi
```

```
END
```

SKRIPSI

PAGE 1

```

1
$MOD51                                ; model seri mikrokontrol 51
0000                                2      ORG      0000H                ;
alamat mulai program
0000 2100                            3      AJMP   START                ;
lompat absolut ke START
0023                                4
0023H                                5      ORG
; alamat Interupsi Serial Terima/Kirim RI/TI
0023 2107                            6      AJMP   Serial_on          ;
lompat absolut ke Serial_on
0100                                7
0100                                8      ORG
0100H                                ; lompat absolut ke 100h
0100 758130                          9      START: MOV   SP, #30H      ; isi
Stack Pointer dengan nilai 30h
0103 7C30                             10     MOV    R4,
#30H                                ; isi Stack Pointer dengan nilai 30h
0105 31C7                             11     ACALL  INITSER            ;
lompat absolut ke initserial
12
13
0107 C0D0                             14     Serial_on: PUSH  PSW
0109 C0E0                             15     PUSH  ACC
010B 3098FD                           16     JNB
RI,$                                ; menunggu data serial masuk
010E E599                             17     MOV   A, SBUF
0110 C298                             18     CLR
RI                                ; clear bit Receiver Interupt
0112 C2AF                             19     CLR
EA                                ; clear bit Enable Interupt
0114 B47705                           20     CJNE
A, #'w', KR45                        ;
0117 314F                             21     ACALL  MAJU20
0119 31DE                             22     ACALL  X_Serial
011B 32                                23
RETI                                ; kembali ke interpsi
24
011C B46D04                           25     KR45: CJNE  A, #'m', KR90   ; bandingkan
dengan 'm', tidak sama lompat kr KR90
011F 3160                             26     ACALL  KIRI45                ;
jika sama laksanakan lakukan KIRI45
0121 31DE                             27     ACALL  X_Serial                ;
Kirim Informasi ke PC
28

```


0178	C287	77		CLR		P0.7
017A	31BA	78		ACALL	DELAY	
017C	31AD	79		ACALL	BREAK	
		80				
017E	75A00F	81	KIRI90: MOV			P2, #00001111B
0181	D281	82		SETB	P0.1	
0183	C286	83		CLR		P0.6
0185	C280	84		CLR		P0.0
0187	D287	85		SETB	P0.7	
0189	31BA	86		ACALL	DELAY	
018B	31AD	87		ACALL	BREAK	
		88				
018D	75A0F0	89	KANAN90:MOV			P2, #11110000B
0190	C281	90		CLR		P0.1
0192	D286	91		SETB	P0.6	
0194	D280	92		SETB	P0.0	
0196	C287	93		CLR		P0.7
0198	31BA	94		ACALL	DELAY	
019A	31AD	95		ACALL	BREAK	
		96				
019C	75A03C	97	MUNDUR20:MOV			P2, #00111100B
019F	C281	98		CLR		P0.1
01A1	C286	99		CLR		P0.6
01A3	D280	100		SETB	P0.0	
01A5	D287	101		SETB	P0.7	
01A7	31BA	102		ACALL	DELAY	
01A9	31BA	103		ACALL	DELAY	
01AB	31AD	104		ACALL	BREAK	
		105				
01AD	C281	106	BREAK: CLR		P0.1	
01AF	C280	107		CLR	P0.0	
01B1	C286	108		CLR	P0.6	
01B3	C287	109		CLR	P0.7	
01B5	75A0FF	110		MOV		P2, #11111111B
01B8	31BA	111		ACALL	DELAY	
		112				
		113				

114

; routine tunda waktu

01BA 7D04 115 DELAY: MOV R5, #04H ; Isi nilai

Register ke-5 dengan 04h

SKRIPSI

PAGE 3

01BC 7EFF 116 DEL1: MOV R6, #0FFH ; Isi nilai

Register ke-6 dengan 0ffh atau 254

01BE 7FFF 117 DEL2: MOV R7, #0FFH ; Isi nilai

Register ke-7 dengan 0ffh atau 254

01C0 DFFE 118 DJNZ R7, \$; kurangi 1

register ke-7

01C2 DEFA 119 DJNZ R6, DEL2 ; kurangi 1

```

register ke-6, bila hasil belum sama dengan 0 ma
    ka lompat ke DEL2
        01C4 DDF6          120          DJNZ    R5, DEL1          ; kurangi 1
register ke-5, bila hasil belum sama dengan 0 ma
    ka lompat ke DEL1
        01C6 22           121
RET          ; kembali ke alamat setelah ACALL DELAY
        122
        01C7           123    INITSER:          ;
routine Inisialisasi Serial
        01C7 759850      124          MOV     SCON, #50H          ;
serial port mode bit 1 & Receiver Enable
        01CA 758920      125          MOV     TMOD, #20H          ;
Timer 1 mode 2; 8-bit auto-reload
        01CD 758BFD      126          MOV     TL1, #0FDH          ;
Timer Low, nilai akan berhitung sampai #0FFH
        01D0 758DFD      127          MOV     TH1, #0FDH          ;
Timer High Reset, Nilai = #0FDH
        01D3 D28E        128          SETB   TR1                  ;
Timer 1 RUN
        01D5 758700      129          MOV     PCON, #00H          ;
hidupkan power control
        01D8 75A890      130          MOV     IE, #90H           ;
Enable Serial Port Interrupt
        01DB D2AC        131          SETB   ES
        01DD 22          132
RET          ; kembali ke alamat setelah ACALL INITSER
        133
        134
        01DE F599        135    X_Serial:    MOV     SBUF, A ; pindahkan
isi accumulator k buffer port serial
        01E0 3099FD      136          JNB    TI, $              ;
jeda hingga bit RI diatur
        01E3 C299        137          CLR
TI          ; clear Transmit Interupsi
        01E5 D2AF        138          SETB   EA                  ; Set
bit Enable Interupt
        01E7 32          139          RETI          ;
kembali ke interpsi
        140
        141
        142          END
    
```

VERSION 1.2h ASSEMBLY COMPLETE, 0 ERRORS FOUND

SKRIPSI

PAGE 4

ACC. D ADDR 00E0H PREDEFINED
 BREAK. C ADDR 01ADH

DEL1	C ADDR	01BCH	
DEL2	C ADDR	01BEH	
DELAY.	C ADDR	01BAH	
EA	B ADDR	00AFH	PREDEFINED
ES	B ADDR	00ACH	PREDEFINED
EXIT	C ADDR	0148H	
IE	D ADDR	00A8H	PREDEFINED
INITSER.	C ADDR	01C7H	
KANAN45.	C ADDR	016FH	
KANAN90.	C ADDR	018DH	
KIRI45	C ADDR	0160H	
KIRI90	C ADDR	017EH	
KN45	C ADDR	012AH	
KN90	C ADDR	0131H	
KR45	C ADDR	011CH	
KR90	C ADDR	0123H	
MAJU20	C ADDR	014FH	
MD	C ADDR	0138H	
MUNDUR20	C ADDR	019CH	
P0	D ADDR	0080H	PREDEFINED
P2	D ADDR	00A0H	PREDEFINED
PCON	D ADDR	0087H	PREDEFINED
PSW.	D ADDR	00D0H	PREDEFINED
RI	B ADDR	0098H	PREDEFINED
SBUF	D ADDR	0099H	PREDEFINED
SCON	D ADDR	0098H	PREDEFINED
SERIAL_ON.	C ADDR	0107H	
SP	D ADDR	0081H	PREDEFINED
START.	C ADDR	0100H	
STOP	C ADDR	013FH	
TH1.	D ADDR	008DH	PREDEFINED
TI	B ADDR	0099H	PREDEFINED
TL1.	D ADDR	008BH	PREDEFINED
TMOD	D ADDR	0089H	PREDEFINED
TR1.	B ADDR	008EH	PREDEFINED
X_SERIAL	C ADDR	01DEH	

:020000002100DD
:020023002107B3
:100100007581307C3031C7C0D0C0E03098FDE599B2
:10011000C298C2AFB47705314F31DE32B46D0431CD
:100120006031DEB46C04317E31DEB47404316F3181
:10013000DEB47204318D31DEB46604319C31DEB43C
:10014000730631AD31AD31DEF599D0E0D0D032D289
:1001500081D286C280C28775A0C331BA31BA31ADAF
:1001600075A0CFD281C286C280C28731BA31AD7547
:10017000A0F3C281D286C280C28731BA31AD75A0E8
:100180000FD281C286C280D28731BA31AD75A0F05C
:10019000C281D286D280C28731BA31AD75A03CC24D
:1001A00081C286D280D28731BA31BA31ADC281C222
:1001B00080C286C28775A0FF31BA7D047EFF7FFFB3
:1001C000DFFEDEFADDF622759850758920758BFD0D
:1001D000758DFDD28E75870075A890D2AC22F599E9
:0801E0003099FDC299D2AF3243
:00000001FF



```

Dim i As Integer
Dim huruf As String
Private Sub clear()
Text1.Text = ""
Text2.Text = ""
End Sub
Private Sub Command1_Click()
huruf = "m"
Text1.Text = Text1.Text + huruf
End Sub

Private Sub Command2_Click()
huruf = "l"
Text1.Text = Text1.Text + huruf
End Sub

Private Sub Command3_Click()
huruf = "w"
Text1.Text = Text1.Text + huruf
End Sub

Private Sub Command4_Click()
huruf = "t"
Text1.Text = Text1.Text + huruf
End Sub

Private Sub Command5_Click()
huruf = "r"
Text1.Text = Text1.Text + huruf
End Sub

Private Sub Command6_Click()
'MSComm1.Output = Text1.Text
End Sub

Private Sub Command7_Click()
clear
Text1.SetFocus
End Sub

Private Sub Command8_Click()
End
End Sub

Private Sub Command9_Click()
huruf = "s"
Text1.Text = Text1.Text + huruf
End Sub

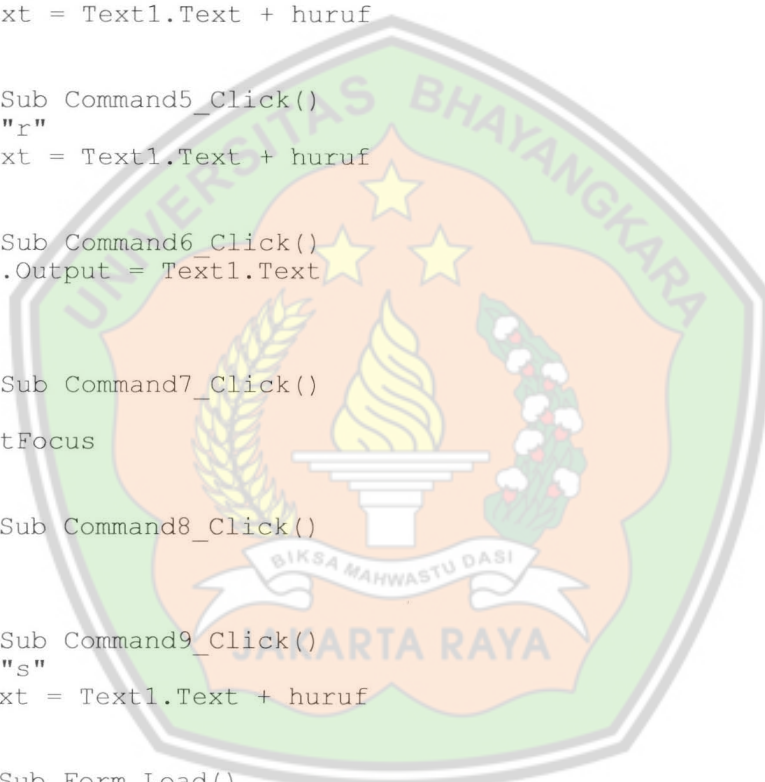
Private Sub Form_Load()
MSComm1.CommPort = 1
MSComm1.Settings = "9600,N,8,1"
MSComm1.InputLen = 0
'MSComm1.PortOpen = True
clear
End Sub

Private Sub Form_KeyPress(KeyAscii As Integer)
MSComm1.Output = KeyAscii
Text1.Text = KeyAscii
End Sub

Private Sub MSComm1_OnComm()
If (MSComm1.CommEvent = comEvReceive) Then
Text2.Text = MSComm1.Input
End If
End Sub

Private Sub Form_Unload(Cancel As Integer)

```



```
'MSComm1.PortOpen = False  
End Sub
```



Form1

Kirim

Terima

Kirim 45

Kirim 45

Stop

Hand icon

Yellow star

Red X icon



